Neural Guided Program Synthesis AAAI'22 & JOSS'22 with N.Fijalkow, G.Lagarde, T.Matricon, K.Ellis, P.Ohlmann, A.Potta

Séminaire LINKS - 05/04/2024

Program Synthesis?

An old dream: Church's Problem (1957)













Similarities with machine learning



Learning algorithm

Model

Similarities with machine learning





Program Synthesis

Small number of examples

Combinatorial/Symbolic search

Satisfies all specifications (reliable)

Program (interpretable)

Learning algorithm

Model

Machine learning

Large amount of data

Optimisation

Minimizes a loss function (noisy)

Model (hard to understand)

DeepCoder

Microsoft (Balog et al., 2017) — it manipulates list of integers

Program 4:

- $x \leftarrow [int]$ $y \leftarrow [int]$ [7 3 8 2 5], $c \leftarrow SORT x$ [2 8 9 1 3] $d \leftarrow SORT y$ $e \leftarrow REVERSE d$
- $f \leftarrow ZIPWITH (*) de$
- $g \leftarrow SUM f$

Input-output example: Input:

- Output:
- 79

Description:

Xavier and Yasmine are laying sticks to form non-overlapping rectangles on the ground. They both have fixed sets of pairs of sticks of certain lengths (represented as arrays x and y of numbers). Xavier only lays sticks parallel to the x axis, and Yasmine lays sticks only parallel to y axis. Compute the area their rectangles will cover at least.

Google (Shi et al. 2019) — it manipulates tensors in Tensorflow

```
# Input-output example
inputs = {
    'scores': [[0.7, 0.2, 0.1],
              [0.4, 0.5, 0.1],
               [0.4, 0.4, 0.2],
               [0.3, 0.4, 0.3],
               [0.0, 0.0, 1.0]],
}
output = [[1, 0, 0]],
          [0, 1, 0],
          [1, 0, 0],
          [0, 1, 0],
          [0, 0, 1]]
```

TF-Coder uses a combination of <u>tf.one_hot</u> and <u>tf.argmax</u> in a short solution to this problem:

TF-Coder

```
tf.cast(tf.one_hot(tf.argmax(scores, axis=1), 3), tf.int32)
```

ARC Dataset

« The Abstraction and Reasoning Corpus », in « On the measure of intelligence » François Chollet, 2019











Neural-Guided Program Synthesis Combination of formal methods and machine learning







First practical instance: DeepCoder, 2017

Natural idea: patterns found in examples reveal which primitives are used in a solution program

$$[1, 5, 4, 2] \longrightarrow [2, 4]$$
$$[6, 3, 0, 8] \longrightarrow [0, 6, 8]$$

Likely primitives such that:

- SORT
- FILTER[EVEN]
- MULTIPLY[2]
- •

Program representation

DSL: domain specific language

- Designed for a specific class of tasks
- List of primitives + associated types + semantics

DSL

```
sort:list(int) \rightarrow list(int)
car:list(t) \rightarrow t
cdr:list(t) \rightarrow list(t)
map:(t1 \rightarrow t2) \rightarrow
list(t1) \rightarrow list(t2)
range:int \rightarrow list(int)
+:int \rightarrow int \rightarrow int
1:int
```

SyGUS in its own words

The Problem

A Syntax-Guided Synthesis problem (SyGuS, in short) is specified with respect to a background theory \mathbb{T} , such as Linear-Integer-Arithmetic (LIA), that fixes the types of variables, operations on types, and their interpretation.

To synthesize a function f of a given type, the input consists of two constraints: (1) a semantic constraint given as a formula φ built from symbols in theory \mathbb{T} along with f, and (2) a syntactic constraint given as a (possibly infinite) set \mathcal{E} of expressions from \mathbb{T} specified by a context-free grammar.

The computational problem then is to find an implementation for the function f, *i.e.* an expression $e \in \mathcal{E}$ such that the formula $\varphi[f \leftarrow e]$ is valid.



DSL —> Context-free Grammar

DSL

```
sort: list(int) \rightarrow list(int)
\texttt{car}:\texttt{list}(\texttt{t}) \to \texttt{t}
cdr: list(t) \rightarrow list(t)
\texttt{map}: (\texttt{t1} \rightarrow \texttt{t2}) \rightarrow
                 list(t1) \rightarrow list(t2)
range: int \rightarrow list(int)
+: int \rightarrow int \rightarrow int
1:int
```

CFG $\texttt{S} \rightarrow \texttt{I,0}$ I,d \rightarrow one $I,d \rightarrow car_{I}(L[I],d+1)$ $I,d \rightarrow plus(I,d+1; I,d+1)$ d=0,1,2,3,4,5 $L[I], d \rightarrow range(I, d+1)$ L[I], $d \rightarrow var$ if $d \ge 3$ $L[I], d \rightarrow sort(L[I], d+1)$ compilation $L[I], d \rightarrow cdr_{I}(L[I], d+1)$ $\texttt{L[I],d} \rightarrow \texttt{car}_{\texttt{L[I]}}(\texttt{L[L[[I]],d+1})$ $L[I], d \rightarrow map_{I,I}(ItoI, d+1;$ L[I],d+1) d=0,1,2,3,4,5 ItoI,d \rightarrow car_{ItoI}(L[ItoI],d+1) $ItoI,d \rightarrow plus(I,d+1)$

d=0,1,2,3,4,5

Syntactic constraints

program type list(int) \rightarrow int program depth ≤ 6 type size ≤ 10 type nesting ≤ 4 variable depth ≥ 3 no two consecutive sort

From CFG to PCFG



3.....

From CFG to PCFG







From CFG to PCFG







A PCFG *induces* a distribution D over **trees = programs**



Predictions: learning the PCFG



- [1, 5, 4, 2] → [2, 4]

A prediction model

Probabilistic weights for the CFG $S \rightarrow \frac{1}{4} \cdot f(S,S) + \frac{3}{4} \cdot g(T)$ $T \rightarrow \frac{2}{3} \cdot a + \frac{1}{3} \cdot b$

Predictions: learning the PCFG



- [1, 5, 4, 2] → [2, 4]
- [6, 3, 0, 8] \longrightarrow [0, 6, 8]

A prediction model



Pr(SORT | FILTER) is high Pr(SORT | REV) is low

Probabilistic weights for the CFG



$$S \to \frac{1}{4} \cdot f(S,S) + \frac{3}{4} \cdot g(T)$$
$$T \to \frac{2}{3} \cdot a + \frac{1}{3} \cdot b$$





The prediction model induces a **prior** distribution D = Pr(program | examples)



Summary so far





How to use predictions for the search?

Toy example on the board

Heap Search.

Bottom-up enumeration strategy preserving the order on programs

- Idea: collections of heaps for storing partial programs
- **Guarantee**: i-th program in time $O(\log i)$

Grammar Splitting.

Divide the search on a parallel architecture

• Idea: partition derivations in a fair way





		$S \xrightarrow{.667} A$			
$\xrightarrow{0}{7} A$		$S \xrightarrow{.333} B$		$S \xrightarrow{.75} B$	
$\xrightarrow{3} C$		$A \xrightarrow{1} H$		$S \xrightarrow{.25} D$	
$\rightarrow F$		$B \xrightarrow{1} I$		$B \xrightarrow{1} J$	
$\rightarrow \dots$	$+.27 \times$	$H \longrightarrow \ldots$	$+$.25 \times	$J \longrightarrow \dots$	
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Heap Search.

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SQRT Sampling.

Optimal sampling strategy with no memory Interesting for simplicity and parallel search

• Idea: sample programs according to $D' \propto \sqrt{D}$

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How to sample? —> Construct a new PCFG for \sqrt{D}

		$S \xrightarrow{.667} A$			
$\xrightarrow{7} A$		$S \xrightarrow{.333} B$		$S \xrightarrow{.75} B$	
$\xrightarrow{3} C$		$A \xrightarrow{1} H$		$S \xrightarrow{.25} D$	
$\rightarrow F$		$B \xrightarrow{1} I$		$B \xrightarrow{1} J$	
$\rightarrow \dots$	$+.27 \times$	$H \longrightarrow \ldots$	$+.25 \times$	$J \longrightarrow \dots$	
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Figure 7: Comparing all search algorithms on the DreamCoder reduced dataset with machine-learned PCFGs

Thanks!

- Generic pipeline to do symbolic sea Learning Predictions
- Check out DeepSynth (open-source tool) <u>https://deepsynth.labri.fr/</u>
- Is heap search optimal (from an enumeration complexity POV)?
- Better sampling if using memory?
- Use feedback to refine the search?

Generic pipeline to do symbolic search on grammars enhanced with Machine

e tool) — <u>https://deepsynth.labri.fr/</u> umeration complexity POV)?



Example
$$G \begin{bmatrix} S \rightarrow \frac{1}{2}f(S,T) & | \frac{1}{2}a \\ T \rightarrow b \end{bmatrix}$$

Natural Cardidate:

for X non-terminal
$$(X = S,T)$$
 define

$$\begin{bmatrix} X \end{bmatrix} = \sum \{ \mathcal{D}(t) : t \text{ generated from } X \}$$

$$\begin{cases} \begin{bmatrix} S \end{bmatrix} = \frac{1}{V2} \begin{bmatrix} S \end{bmatrix} \begin{bmatrix} T \end{bmatrix} + \frac{1}{V2} \\ \begin{bmatrix} T \end{bmatrix} = 1 \end{cases} \Rightarrow \begin{cases} \begin{bmatrix} S \end{bmatrix} = 1 + V \\ \begin{bmatrix} T \end{bmatrix} = 1 \end{cases}$$

$$The PCFG computing VD' is$$

$$IG \begin{bmatrix} S \rightarrow \frac{1}{V+V2} \begin{pmatrix} \frac{1}{V2} f(S,T) \\ T \rightarrow b \end{bmatrix} \xrightarrow{V2} a \end{pmatrix}$$

FG,

